

19-6 Stoke 定理(Stoke's Theorem)

⇨重點整理⇩

1. 空間 Stoke 定理：

D 為第 II 類單連通區間，

$$\vec{f}(x, y, z) = f_1 \vec{i} + f_2 \vec{j} + f_3 \vec{k}$$

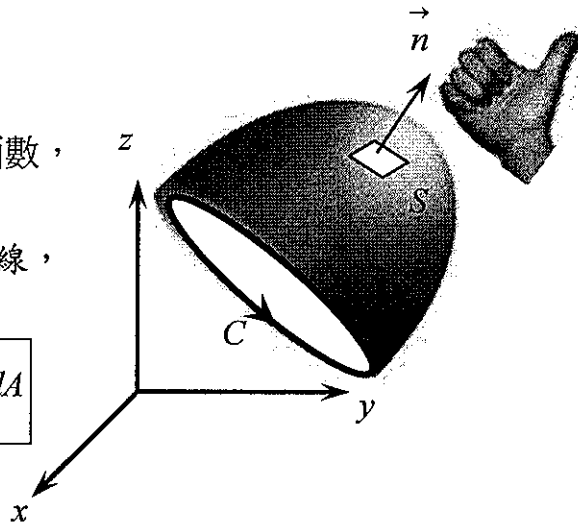
在 D 內為一階連續向量函數，

S 為 D 內之一曲面，

C 為 S 上之一微量封閉曲線，

A 為 C 內部之面積，

$$\text{則 } \oint_C \vec{f} \cdot d\vec{r} = \iint_S (\nabla \times \vec{f}) \cdot \vec{n} dA$$

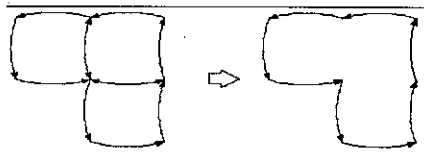


證明 $\text{curl } \vec{f} = \nabla \times \vec{f} = \left(\lim_{A \rightarrow 0} \frac{1}{A} \oint_C \vec{f} \cdot d\vec{r} \right) \vec{e}_{\max} = \left(\lim_{A \rightarrow 0} \frac{1}{A} \oint_C \vec{f} \cdot d\vec{r} \right) \vec{n}$

$$(\nabla \times \vec{f}) \cdot \vec{n} = \lim_{A \rightarrow 0} \frac{1}{A} \oint_C \vec{f} \cdot d\vec{r} \approx \frac{1}{\Delta A} \oint_{\Delta C} \vec{f} \cdot d\vec{r}$$

$$(\nabla \times \vec{f}) \cdot \vec{n} \Delta A \approx \oint_{\Delta C} \vec{f} \cdot d\vec{r}$$

$$\sum_i (\nabla \times \vec{f}) \cdot \vec{n}_i \Delta A_i \approx \sum_i \oint_{\Delta C_i} \vec{f} \cdot d\vec{r}$$



當 $\Delta A_i \rightarrow 0$: $\lim_{\Delta A_i \rightarrow 0} \sum_i (\nabla \times \vec{f}) \cdot \vec{n}_i \Delta A_i \approx \lim_{\Delta C_i \rightarrow 0} \sum_i \oint_{\Delta C_i} \vec{f} \cdot d\vec{r}$

由圖知相鄰部份會相抵消，最後只剩下最外表部份

$$\iint_S (\nabla \times \vec{f}) \cdot \vec{n} dA \approx \oint_C \vec{f} \cdot d\vec{r}$$

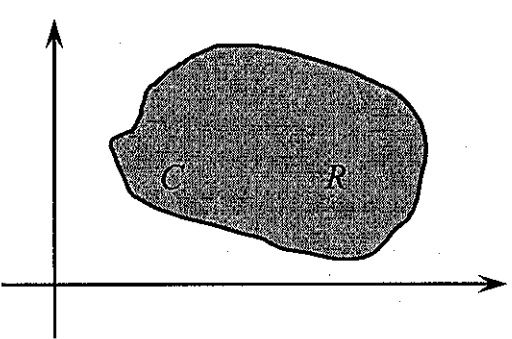
2. 平面 **Stoke** 定理：

R 為單連通區間，且 $\vec{f}(x,y) = f_1\vec{i} + f_2\vec{j}$

在 R 內為一階連續向量函數，

C 為 R 內之一微量封閉曲線，

則 $\oint_C \vec{f} \cdot d\vec{r} = \iint_R (\nabla \times \vec{f}) \cdot \vec{k} dA$



3. **Stoke** 定理之相關定理：

D 為第 II 類單連通區間， $\vec{f}(x,y,z) = f_1\vec{i} + f_2\vec{j} + f_3\vec{k}$

在 D 內為一階連續向量函數，

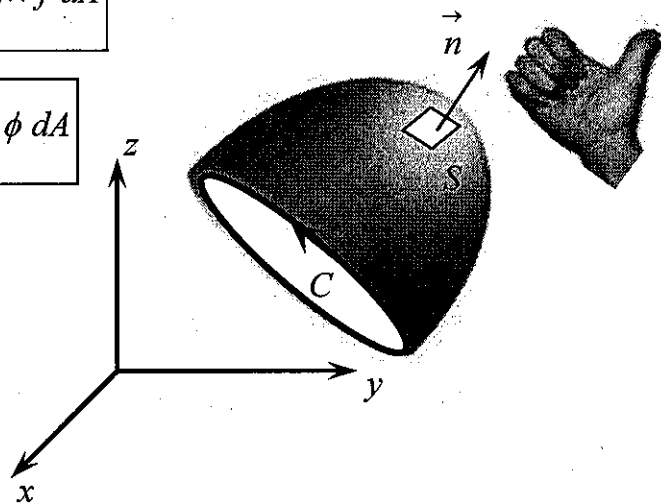
S 為 D 內之一曲面，

C 為 S 上之一微量封閉曲線，則

(1) **Stoke** 定理： $\oint_C \vec{f} \cdot d\vec{r} = \iint_S (\nabla \times \vec{f}) \cdot \vec{n} dA \Rightarrow \oint_C \vec{e}_i \cdot \vec{f} ds = \iint_S (\vec{n} \times \nabla) \cdot \vec{f} dA$

(2) $\oint_C \vec{e}_i \times \vec{f} ds = \iint_S (\vec{n} \times \nabla) \times \vec{f} dA$

(3) $\oint_C \vec{e}_i \cdot \phi ds = \iint_S (\vec{n} \times \nabla) \cdot \phi dA$





題型 1 3-D Stoke 定理

範例 1

Give the vector $\vec{A} = (x^2 - y^2)\vec{i} + 2xy\vec{j}$.

(a) Evaluate the **surface integral** $\int (\nabla \times \vec{A}) \cdot d\vec{\sigma}$ over a rectangle in the (x, y) plane bounded by the lines $x = 0$, $x = a$, $y = 0$, $y = b$,

Here, $d\vec{\sigma}$ is a **surface element vector**.

(b) Evaluate the **line integral** $\oint \vec{A} \cdot d\vec{l}$ around the boundary of the rectangle.

Here, $d\vec{l}$ is a **line element vector**.

(c) Compare the results you have obtained for (a) and (b). What **theorem** of vector analysis is relevant to the conclusion you draw from the comparison? (20%) 【95 台大物理】

【詳解】(a) 已知 $\vec{A} = (x^2 - y^2)\vec{i} + 2xy\vec{j}$

$$\Rightarrow \nabla \times \vec{A} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2 - y^2 & 2xy & 0 \end{vmatrix} = 4y\vec{k}$$

$$\Rightarrow \int \nabla \times \vec{A} \cdot d\vec{\sigma} = \int 4y\vec{k} \cdot \vec{k} \, dx dy = \int 4y \, dx dy = \int_0^b \int_0^a 4y \, dx dy = 2ab^2$$

$$(b) \oint_C \vec{A} \cdot d\vec{l} = \oint_C [(x^2 - y^2)dx + 2xydy]$$

由 **Green theorem**

$$\text{上式} = \iint \left[\frac{\partial}{\partial x}(2xy) - \frac{\partial}{\partial y}(x^2 - y^2) \right] dx dy = \int_0^b \int_0^a 4y dx dy = 2ab^2$$

(c) 比較(a)(b)，得： $\int \nabla \times \vec{A} \cdot d\vec{\sigma} = \oint \vec{A} \cdot d\vec{l}$

符合 **Stoke's theorem** 的結論，本題得證。

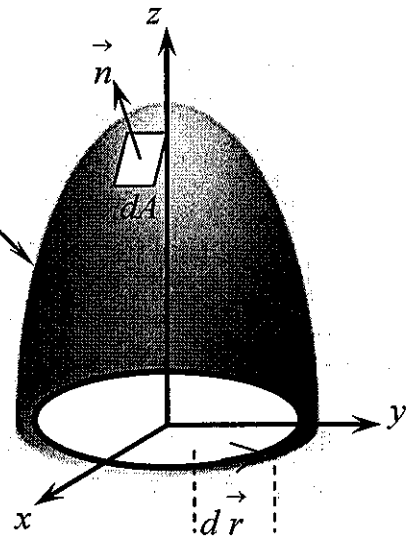
範例 2

Verify the **Stoke's theorem**: $\iint \nabla \times \vec{F} \cdot \vec{n} dA = \oint \vec{F} \cdot d\vec{r}$ (see Fig.)

where the vector function: $\vec{F} = y\vec{i} - z\vec{j} + 3x\vec{k}$;

surface $S: z = f(x, y) = 4 - (x^2 + y^2), z \geq 0$

曲面 $S: z = f(x, y)$



(20%) 【95 成大工科】

【詳解】(1) $\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & -z & 3x \end{vmatrix} = \vec{i} + 3\vec{j} - \vec{k}$

令 $\phi(x, y, z) = x^2 + y^2 + z - 4 = 0$

$\Rightarrow \nabla \phi(x, y, z) = 2x\vec{i} + 2y\vec{j} + \vec{k}$

$\Rightarrow \vec{n} dA = \nabla \phi \frac{dxdy}{|\nabla \phi \cdot \vec{k}|} = (2x\vec{i} + 2y\vec{j} + \vec{k}) dxdy$